

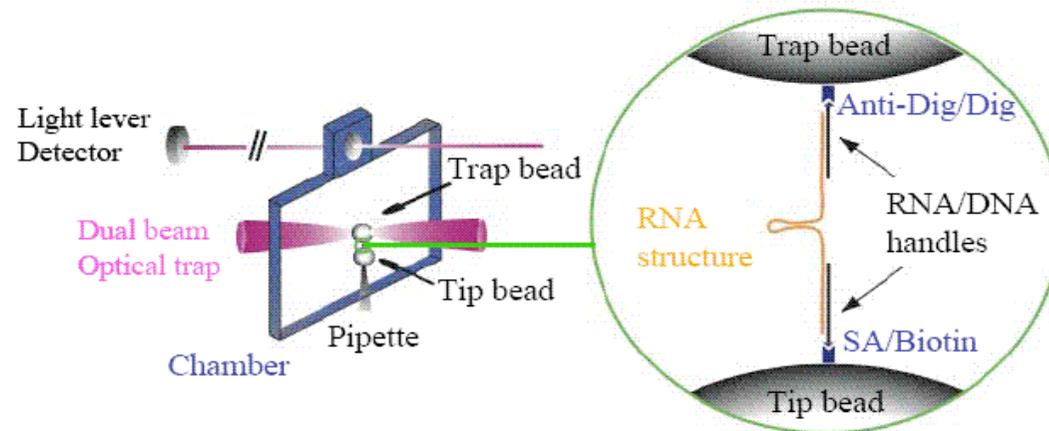
Fluctuations in Small Systems the case of single molecule experiments

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Perugia, Aug. 2nd, 2011

force \times distance $\approx k_B T \gg$ quantum scale

“I do not believe a word he is saying, but I am afraid that one day I will have to learn it” (Bob Silbey)



for an introduction, **C. Bustamante** et al, Physics Today, July 2005, 43-48

Single molecule experiments

(after 1990)

- techniques to measure forces in the pN range (10^{-2} - 10^3)pN, and distances in the nm range (nanodevices);
- with high time resolution to track the trajectories of single biomolecules;
- access to new phenomena in molecular and cellular biophysics → new physical insight in non-equilibrium (n.e.) statistical physics.

The physical problem

Purely mechanical models are too naïve

- energies involved in molecular processes are a few $k_B T$ (at $T=298\text{K}$, $1 k_B T = 4.1\text{pN}\cdot\text{nm} = 0.6\text{kcal/mol}$)

forces $\sim 10\text{pN}$

distances $\sim 1\text{nm}$

Force scale: Brownian, 10fN ; molecular motors, 10pN ; folding (H-bond), 100pN ; covalent bond (1eV for 1\AA), 1nN

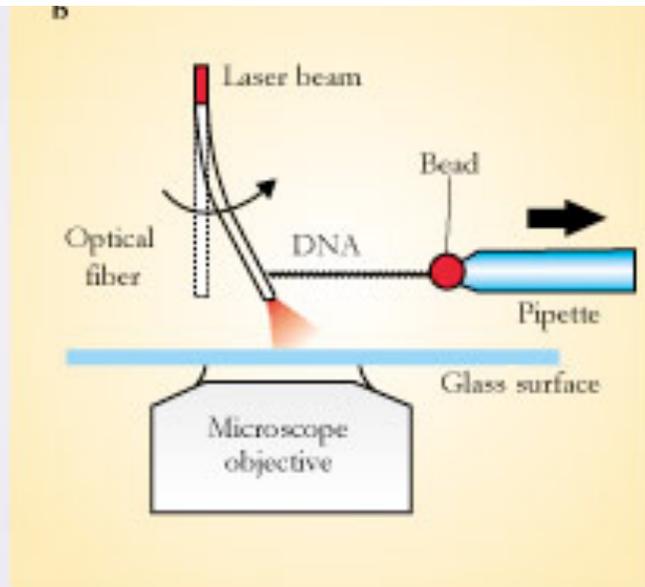
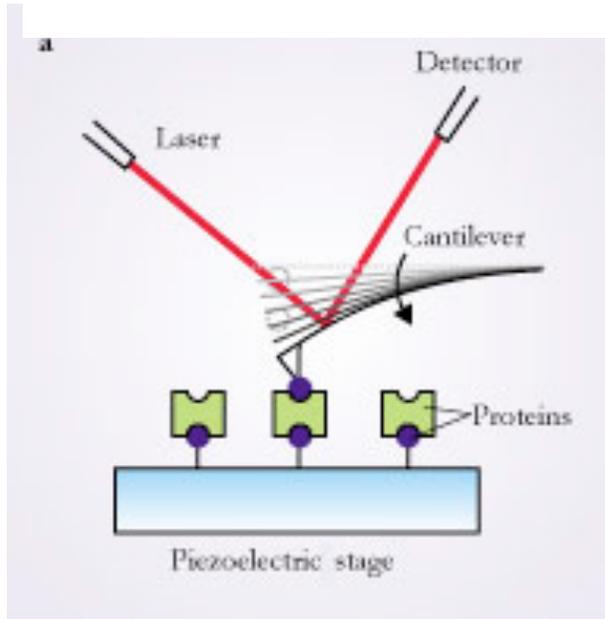
- thermal fluctuations become extremely important as they determine the efficiency of the molecular motors;
- importance of rare events and large deviations from average behavior a new thermodynamics

Mechanochemistry (after 1990)

$$\delta X \delta F \leq k_B T$$

AFM

>10 pN
10⁻³s



$$\langle F \rangle = \kappa \langle X \rangle$$

$$\langle \delta X^2 \rangle = kT/\kappa$$

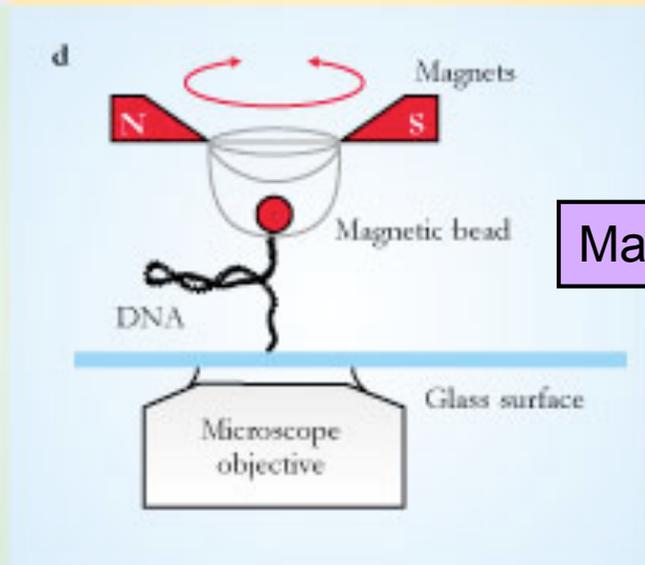
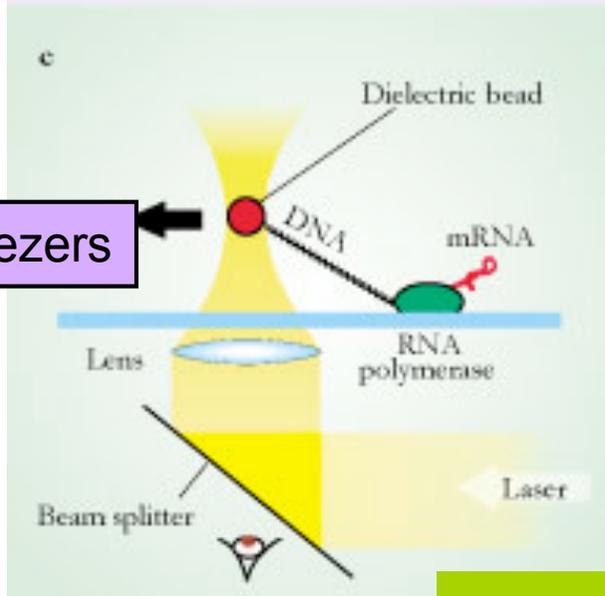
$$\langle \delta F^2 \rangle = \kappa kT$$

$$\langle F \rangle = kT \langle X \rangle / \langle \delta X^2 \rangle$$

1pN

Optical tweezers

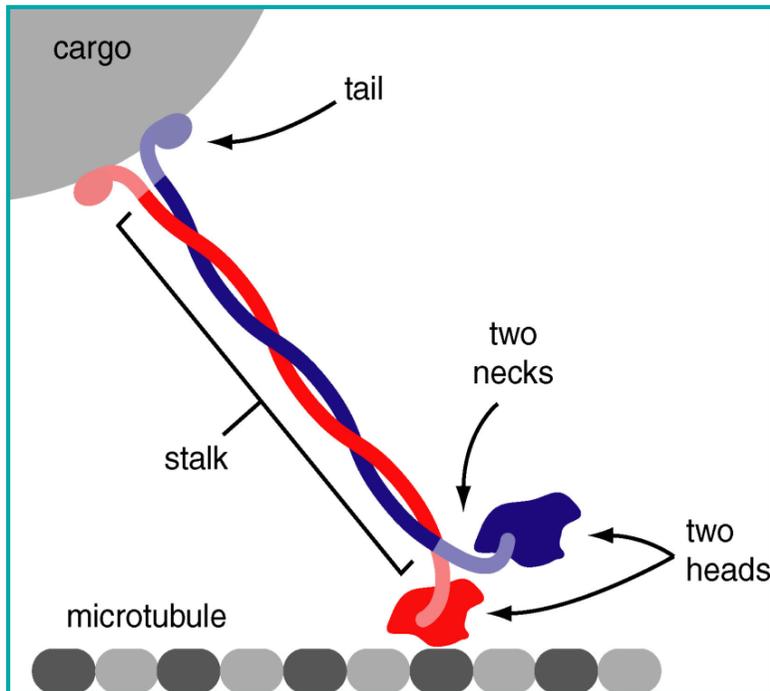
0.1-10²pN
1nm



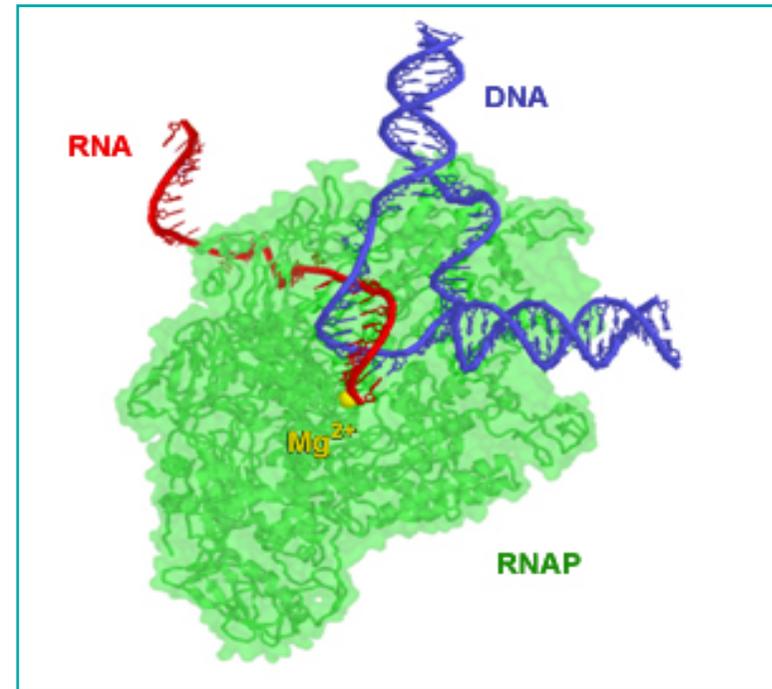
Magnetic tweezers

10⁻²-10pN

Examples



kinesin "walking" along a microtubule,
fueled by ATP hydrolysis



transcription by RNA polymerase
enzyme rectifies thermal noise

fuel: $\text{ATP} \rightarrow \text{ADP} + 20 k_B T$; high efficiency: 40-60% despite pauses, arrests, backtracking events

Small systems

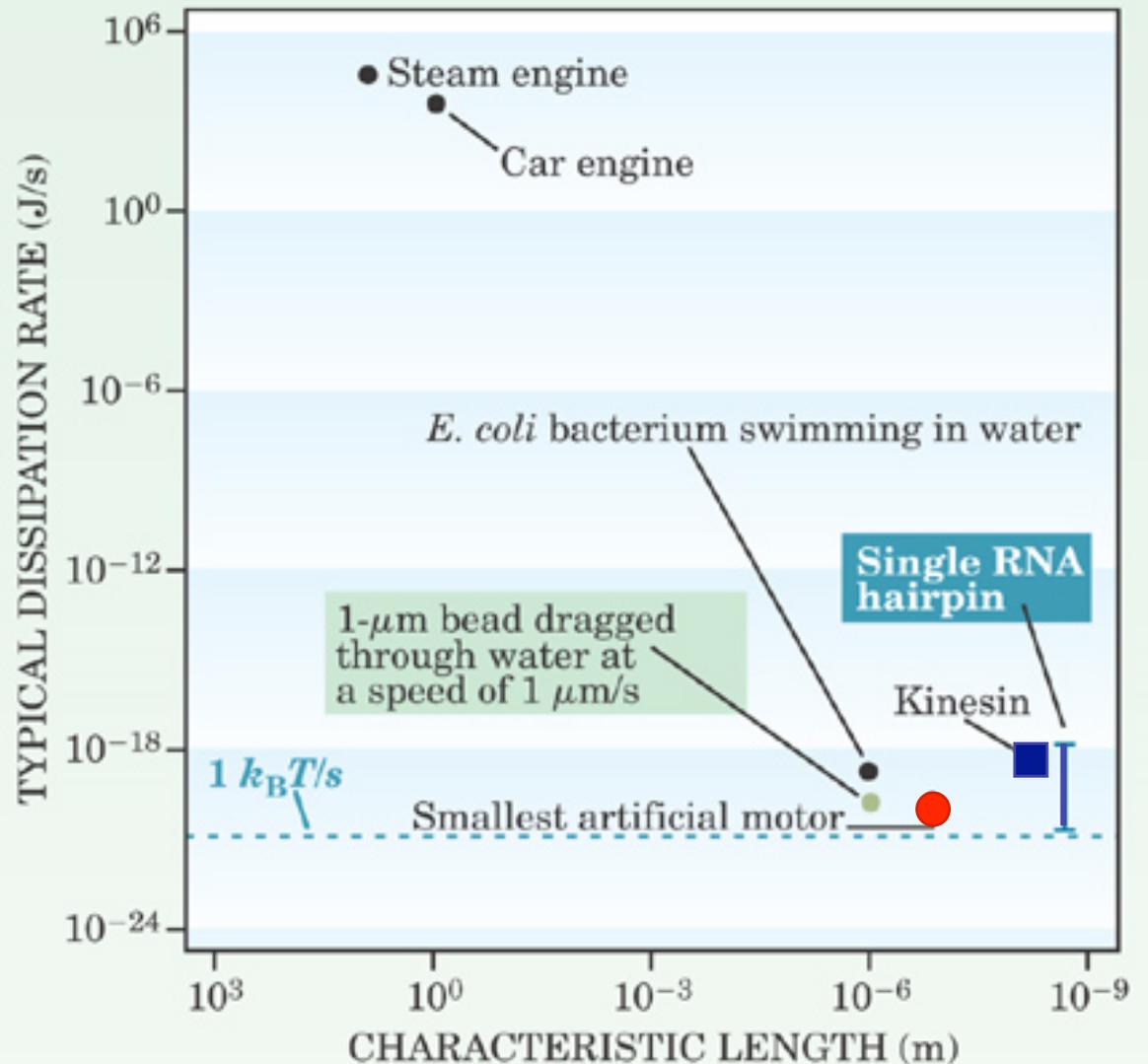
A. Mostly steady state

- net currents across (heat, electric, mass)
- dissipate energy constantly

Example: kinesin

ATP \rightarrow ADP + 20 $k_B T$
1 step: 8nm in 10-15ms
work/step: 12 $k_B T$ (avg. load)

efficiency: ~60%
dissipated pwr.: 650 $k_B T/s$



B. Equation of state and fluctuation depend on the choice of (few) control parameters

in *small* systems
force-extension
characteristics
curves not uniquely
determined

a Control parameter: end-to-end distance X

b Control parameter: external force

a distance X : tunable control parameter;
force on one end/bead: fluctuating variable;
 $A(T, X)$ – Helmholtz f.e.

b force on free end/bead:
tunable control parameter;
chain extension X :
fluctuating variable;
 $G(T, F)$ – Gibbs f.e.

STRETCHED POLYMER

$F = \mu \frac{\partial B_z}{\partial z}$

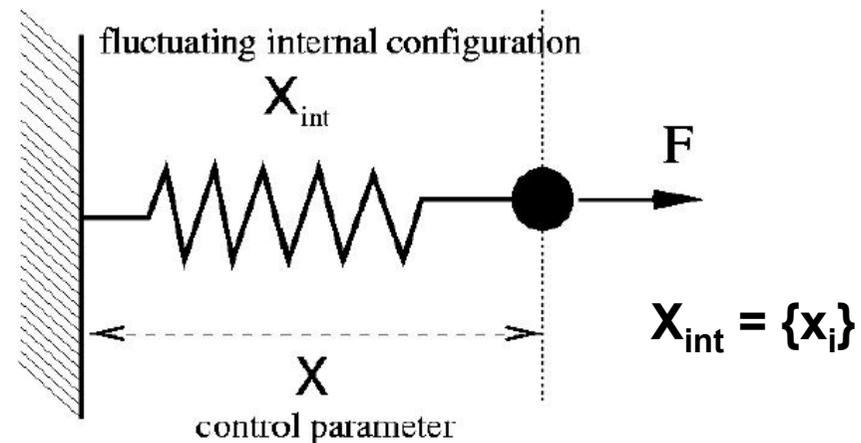
The diagram shows two experimental setups for a stretched polymer. Setup (a) shows a polymer chain between two fixed blue blocks, with a double-headed arrow below indicating the end-to-end distance X . Setup (b) shows a polymer chain attached to a fixed blue block at the top and a green bead at the bottom, with a downward arrow from the bead labeled with the force equation $F = \mu \frac{\partial B_z}{\partial z}$.

control often incomplete

C. Subjected to non-equilibrium transformations...

$$dU = \sum_i \left(\frac{\partial U}{\partial x_i} \right)_X dx_i + \left(\frac{\partial U}{\partial X} \right)_{\{x_i\}} dX = dQ + dW.$$

...according to a given protocol
 $X(t): X_i = 0 \rightarrow X_f$

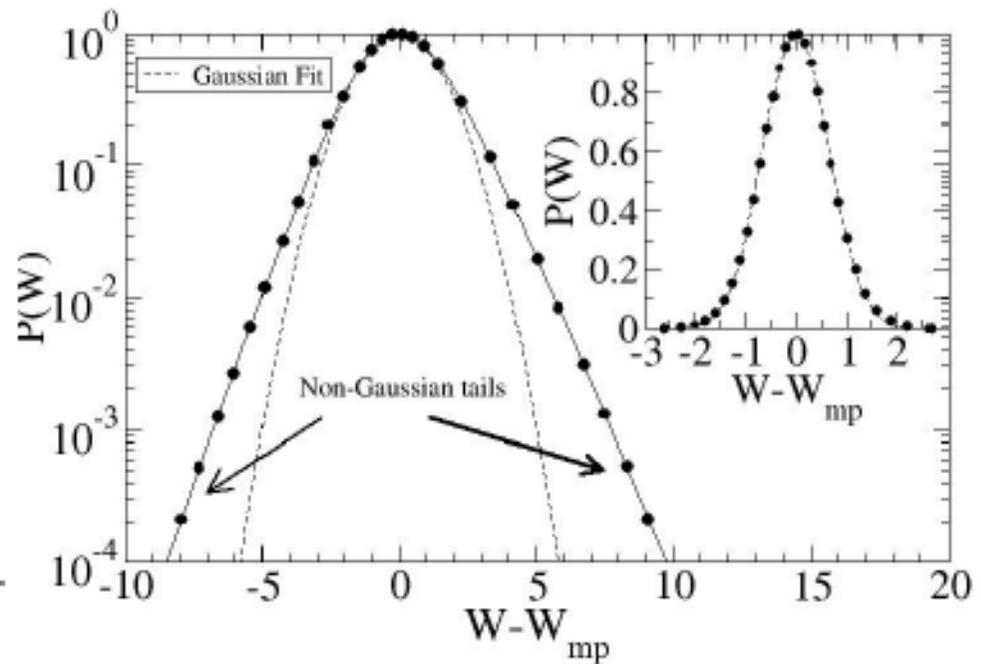
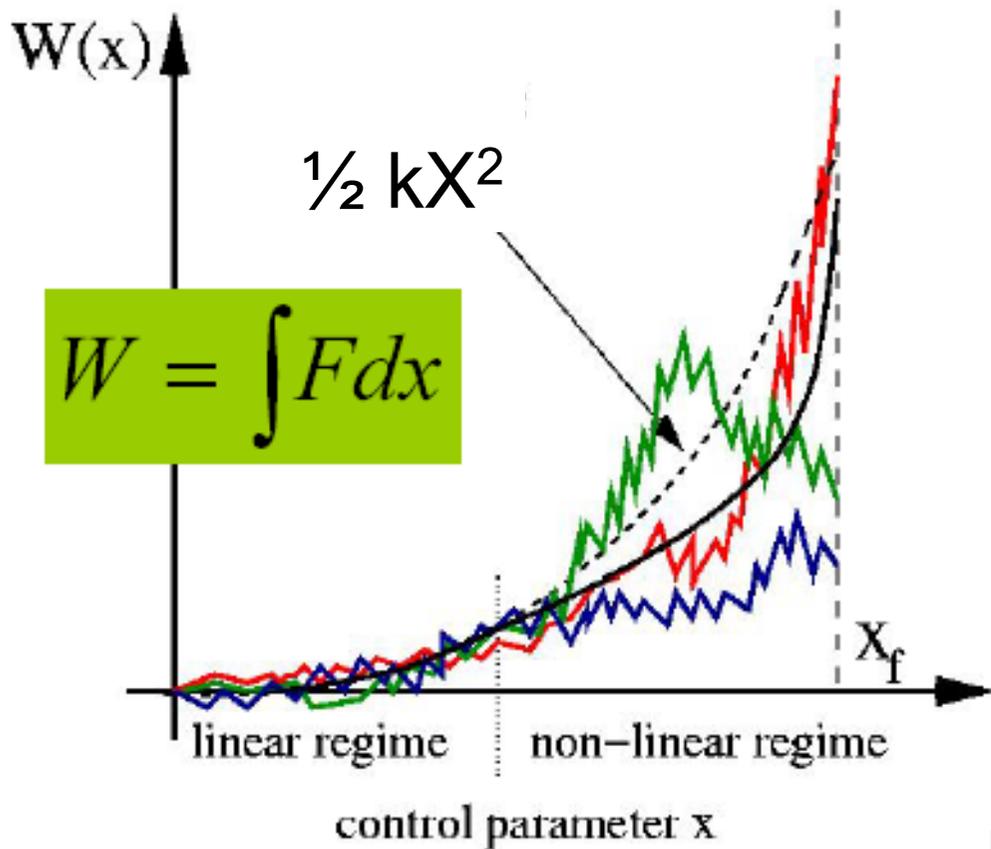


X determines the thermodynamic state of the system

Force $F = F(X_{\text{int}}, X)$ is the fluctuating variable

Q hard to measure \rightarrow
 [for aperiodic $X(t)$]

$$W = \int_0^{X_f} dW = \int_0^{X_f} F dX,$$



F. Ritort, J. Stat. Mech. (Theor. and Exp.) P10016 (2004)

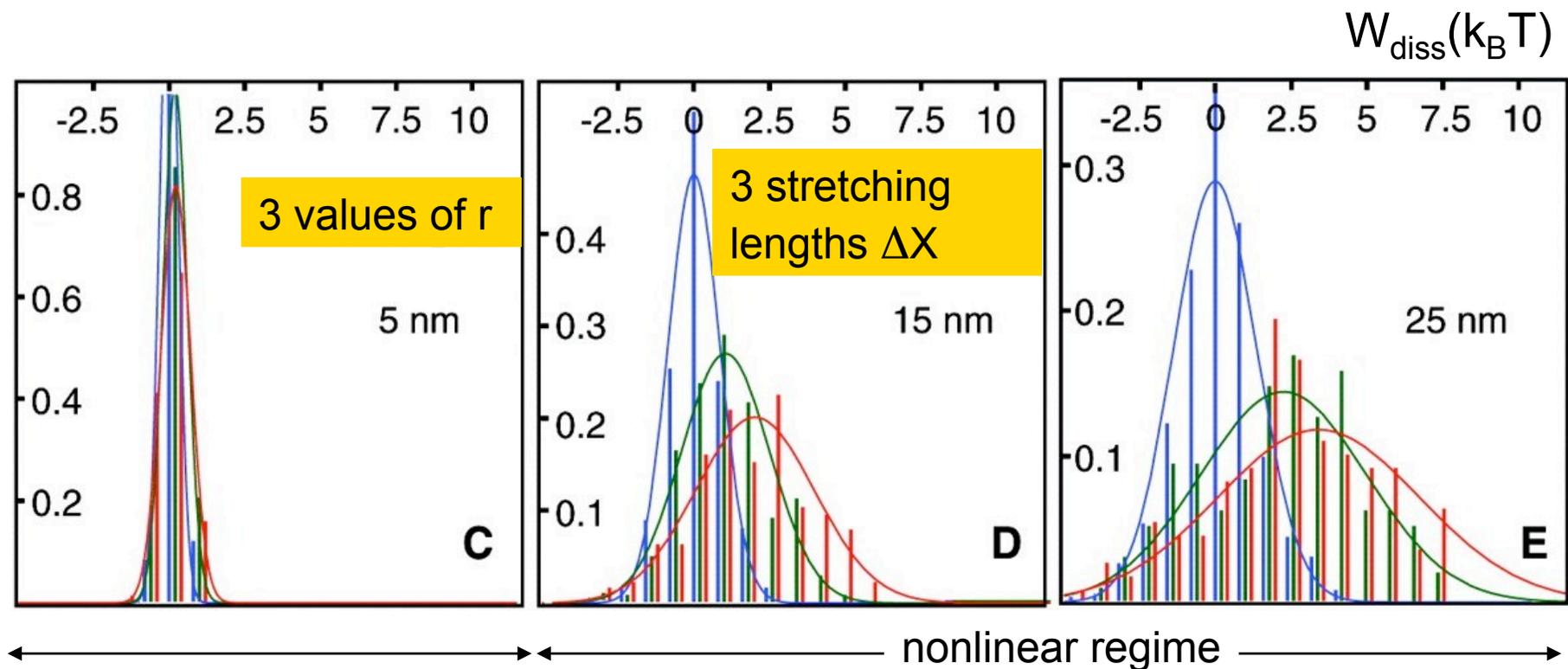
$P(W)$

Work probability distribution

Importance of large and rare deviations respect to the average behavior:

- linear contributions from the *entropy loss* due to the stretching of the molecular handles and of the *elastic stretching* of single-stranded RNA

$P(W)$ exhibits negative “fat” tails



Fluctuation Theorems

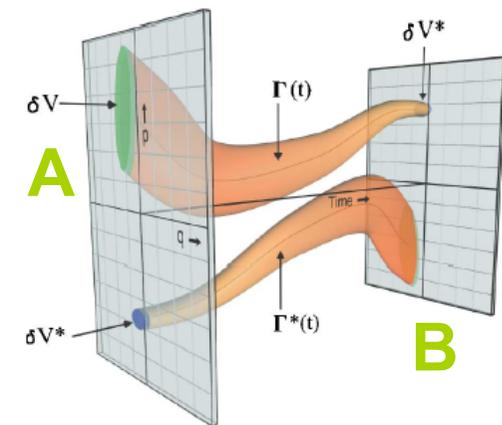
- $\Lambda_F(t)$: n.e. forward process $\lambda_F(\mathbf{t})$: $\lambda_A \rightarrow \lambda_B$; T constant;
A: equilibrium initial state, $t = t_i$; **B***: n.e. final state, $t = t_f$
- $\Lambda_R(t)$: n.e. reverse process $\lambda_R(\mathbf{t}^{\boxminus})$: $\lambda_B \rightarrow \lambda_A$
B: equilibrium initial state, $t^{\boxminus} = t_i$; **A***: n.e. final state, $t^{\boxminus} = t_f$
- $\Delta G = G_B - G_A$ free energy difference between equilibrium states A and B
- $\Lambda_R(t)$ is time reversed with respect to $\Lambda_F(t)$, i.e. $\Lambda_R(s) = \Lambda_F(t-s)$ for $0 \leq s \leq t$, with corresponding work p.d. $P_F(W)$ and $P_R(W)$

$$\frac{P_F(W)}{P_R(-W)} = \exp\left(\frac{W - \Delta G}{k_B T}\right)$$

(Crooks, 1999)

NB: for reversible $\lambda(t)$

$$\Delta G = W_{rev}$$



applies to cyclostationary protocols, too

The Jarzynski Equality (1997)

Re-write Crooks' FT as

$$\begin{aligned} P_R(-W) &= P_F(W) \exp[-(W-\Delta G)/k_B T] \\ &= P_F(W) \exp[-W_{\text{dis}}/k_B T] \end{aligned}$$

$$W - \Delta G = W_{\text{dis}}$$

and integrate $\left\langle \exp\left(-\frac{W_{\text{dis}}}{k_B T}\right) \right\rangle = 1$ **or**

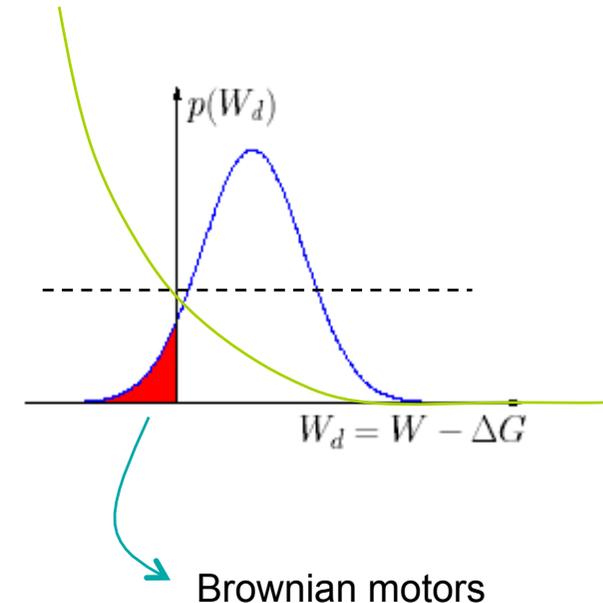
$$\exp\left(-\frac{\Delta G}{k_B T}\right) = \left\langle \exp\left(-\frac{W}{k_B T}\right) \right\rangle$$

The FT physics

$$\left\langle \exp\left(-\frac{W_{\text{dis}}}{k_B T}\right) \right\rangle = 1$$

- free-energy differences can be extracted from nonequilibrium data;
- $\langle W \rangle \geq \Delta G$, or equivalently, $\langle W_{\text{dis}} \rangle \geq 0$, that is the II Law of (macroscopic) thermodynamics. Note that $\langle e^x \rangle \geq e^{\langle x \rangle}$ (Jensen's inequality)
- there must exist trajectories with $W_{\text{dis}} \leq 0$ (red tail) to ensure $\langle \exp(-W_{\text{dis}}/k_B T) \rangle = 1$ -- transient violation of II Law due to t -reversal invariance (Loschmidt);
- non-Gaussian $P(W)$: W -cumulant generating function

$$\Delta G = ? = \langle W \rangle - \langle \sigma^2_W \rangle / 2k_B T$$
 beyond standard *fluctuation-dissipation theorem*.



$$\frac{\Delta G}{k_B T} = -\ln \left\langle \exp\left(-\frac{W}{k_B T}\right) \right\rangle$$

Experimental verification

- Direct method: JE

From the JE

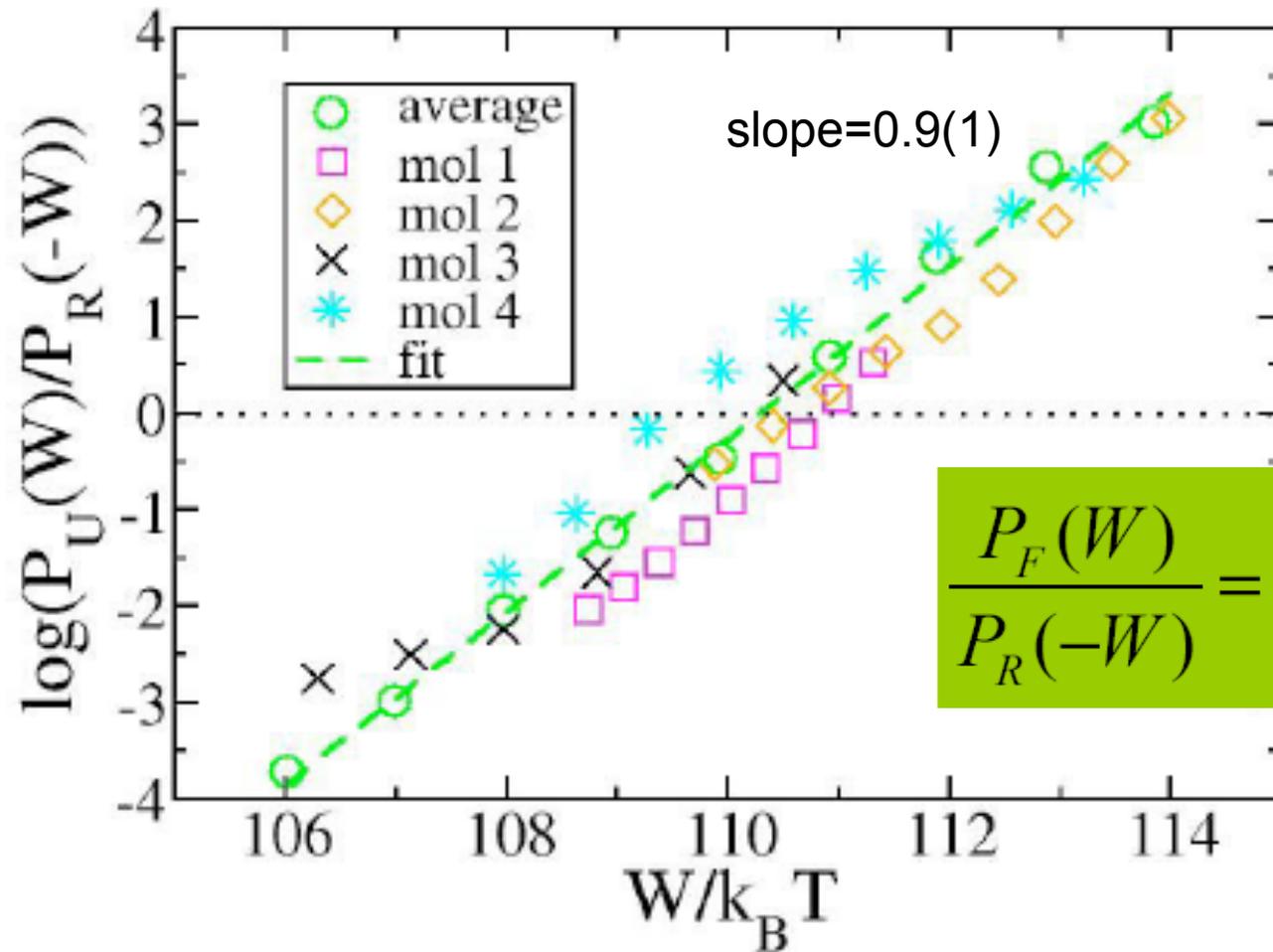
$$\Delta G = -k_B T \ln \left\langle \exp\left(-\frac{W}{k_B T}\right) \right\rangle_F$$

FTs work well only
for small systems!

... for a finite number of experiments this estimate is often biased

Fitted ΔG within a few $k_B T$ of best independent estimates

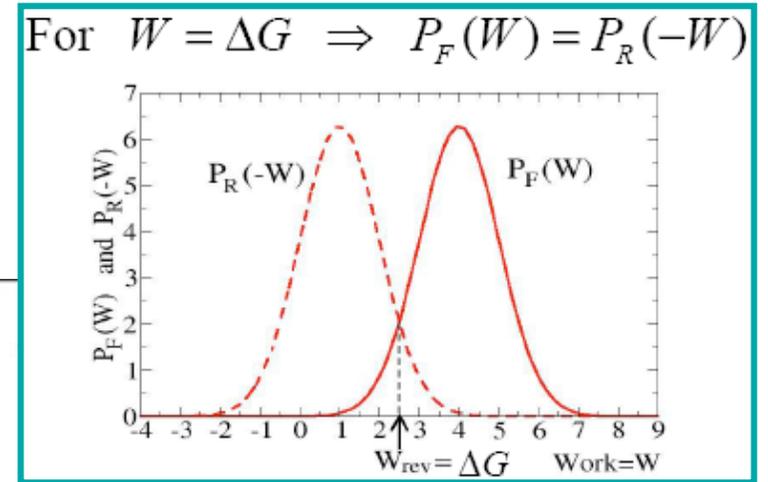
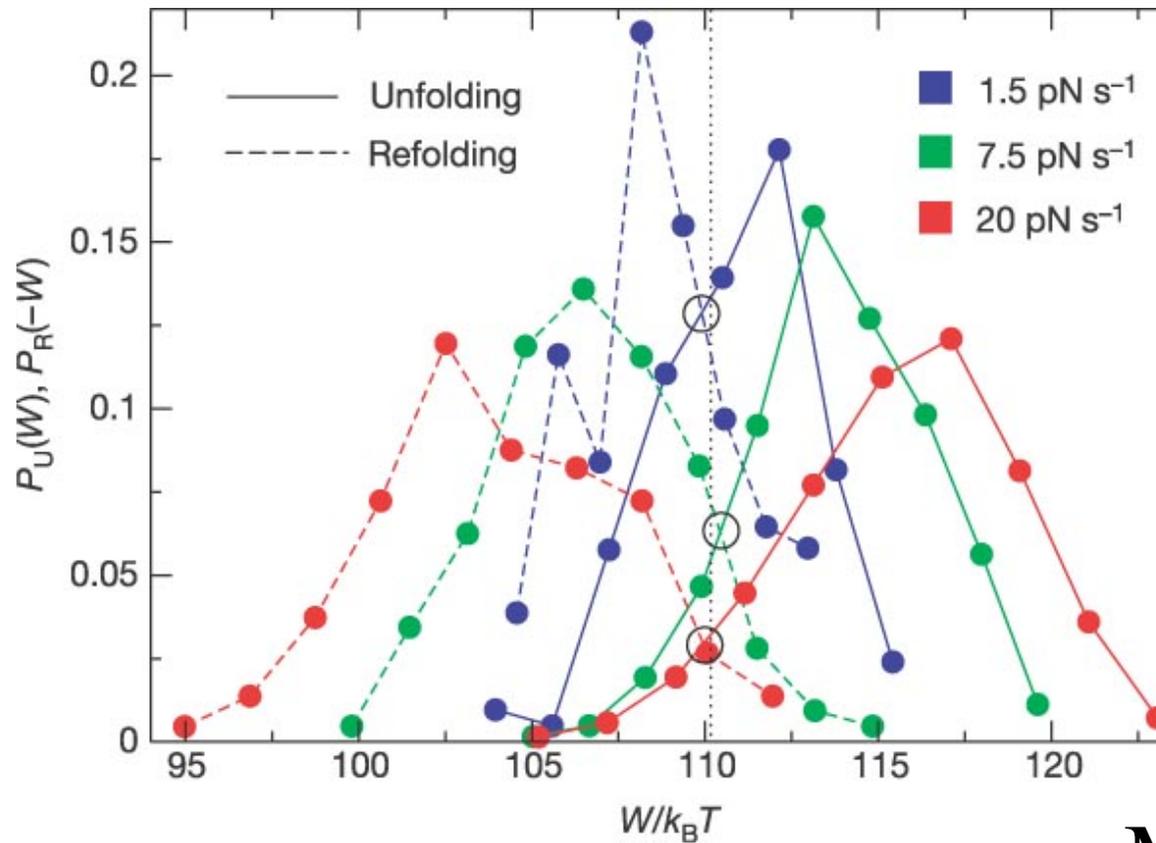
- Direct method: Crooks FT



$$\frac{P_F(W)}{P_R(-W)} = \exp\left(\frac{W - \Delta G}{k_B T}\right)$$

slope close to 1; x-intercept: $\Delta G^{(\text{exp})} \approx 110 k_B T$

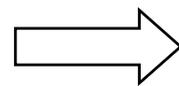
- Crossing method



less systematic error

$$M\text{-fold} = 63.5 k_B T$$

$$\Delta G^{(\text{exp})} = 110.3(5) k_B T$$



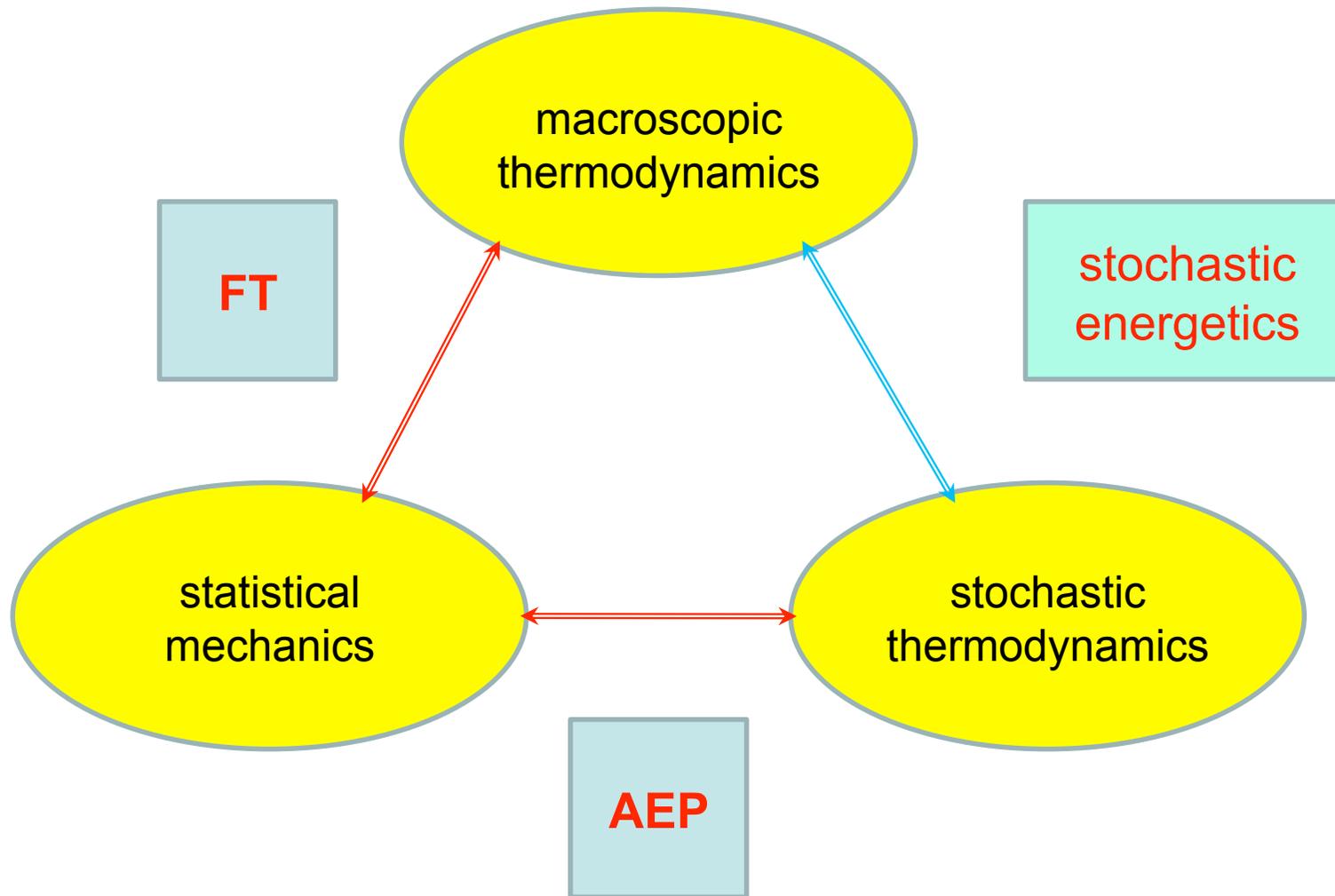
$$\Delta G_0^{(\text{exp})} = 63 \pm 1 k_B T$$

after subtracting entropic handle stretching

difficulties

- experimental determination of small systems, control issues
- operative definition of work (inclusive vs exclusive)
- verification of FT equalities, statistics issues

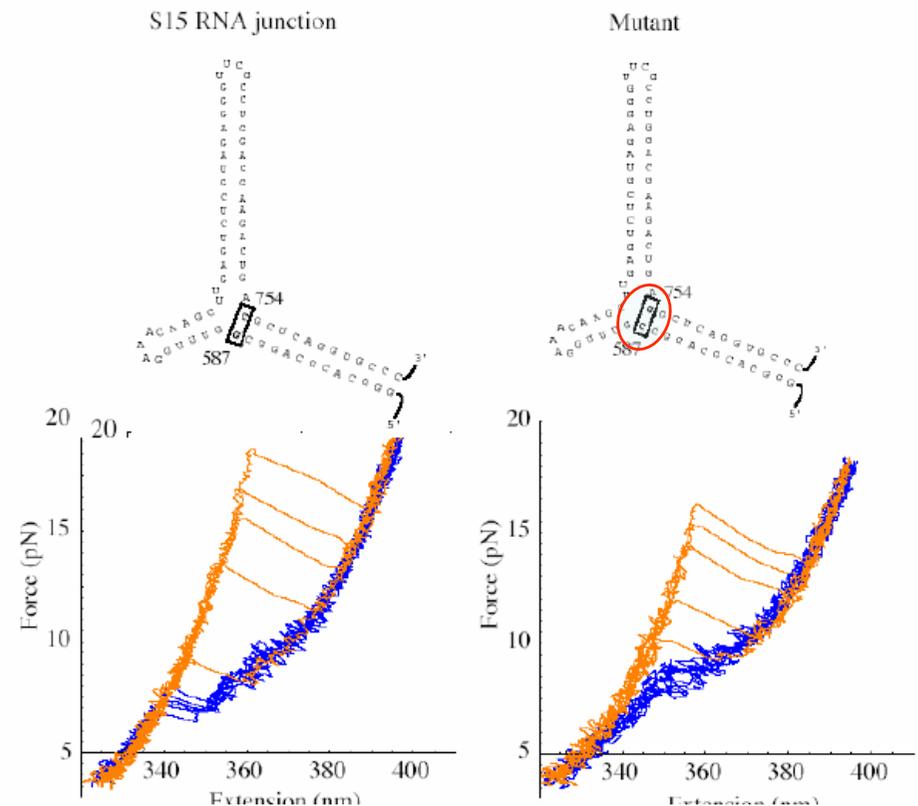
3 levels of description



Conclusions

- a new non-equilibrium thermodynamics of small systems
- more powerful tools to extract information from single molecule experiments
- application to artificial devices (possibly via *stochastic energetics*)

Brownian Motors



References

Reviews:

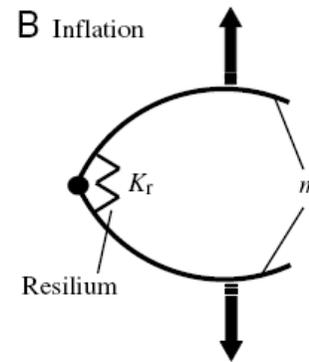
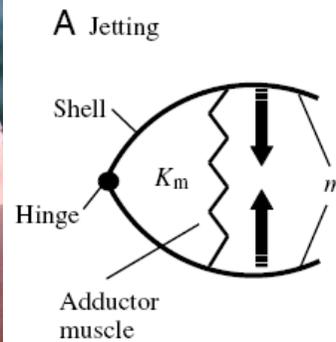
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2. Introduction to fluctuation theorems
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3. F. Ritort, *Séminaire Poincaré* **2**, 193 (2003),
available at <http://arXiv.org/abs/cond-mat/0401311>
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Theorems:

- G. Gallavotti, E. G. D. Cohen, *Phys. Rev. Lett.* **74**, 2694 (1995)
- C. Jarzynski, *Phys. Rev. Lett.* **78**, 2690 (1997)
- G. E. Crooks, *Phys. Rev. E* **60**, 2721 (1999)
- U. Seifert, *Phys. Rev. E* **95**, 040602 (2005)

Brownian motors

from macro to micro scales



scallops, $10^{-2}m$

shell flaps, jets

high Reynolds numbers

$$R = av\rho/\eta \sim 100$$

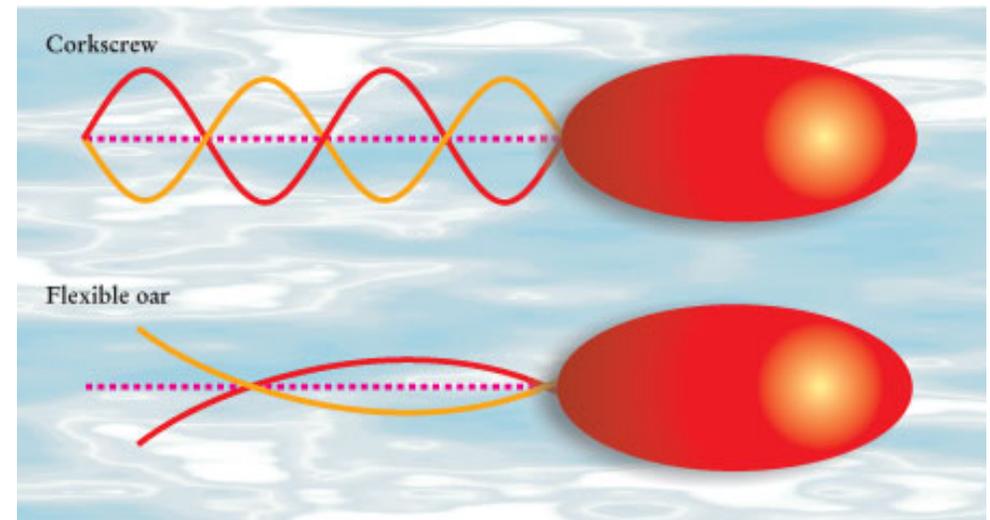
bacteria, $10^{-5}m$

low Reynolds numbers $R \sim 10^{-4}$

flagellum strokes

corkscrew, $v \propto \omega$

flexible oar, $v \propto \omega^2$

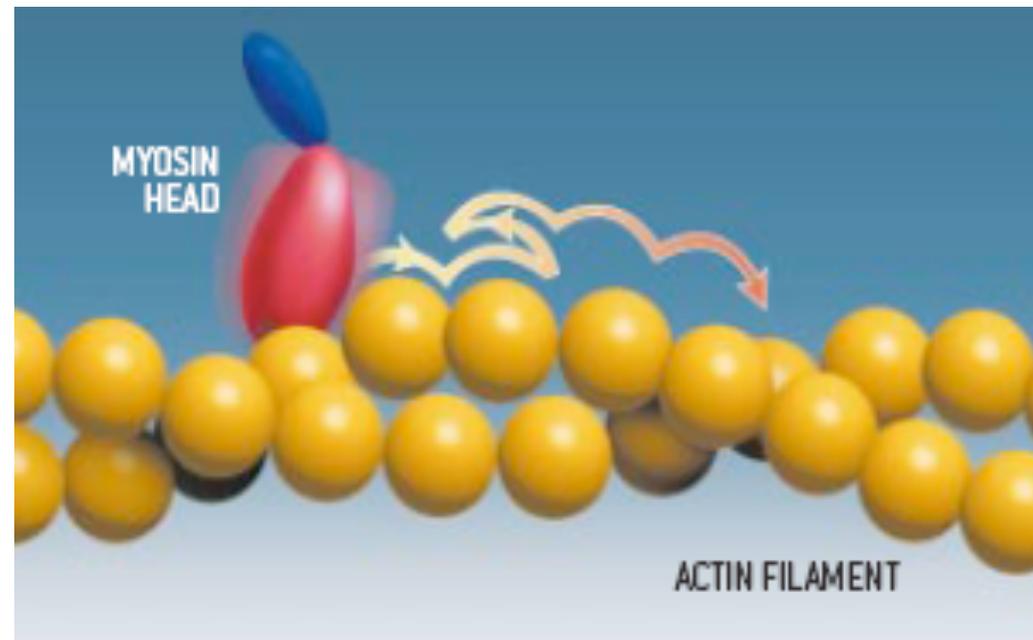


myosin, 10^{-8}m

power strokes: ATP hydrolysis, $\text{ATP} \rightarrow \text{ADP} + 20k_{\text{B}}T$, efficiency $\sim 50\%$;
power from "fuel" comparable with power from/to environment

Brownian motion: time to diffuse a particle length is a^2/D , i.e. much shorter than the drift time a/v — $D = kT/6\pi\eta a$, $v \sim 4\text{-}5\mu\text{m/s}$

not a deterministic engine, rather a directed random walker and still a **very efficient motor!!**
(Yanagida, 1999)



Proof outline:

1. process protocol $\lambda(t): 0 \rightarrow 1$ over a time t_f ; fixed path in system parameter space; heat bath disconnected during evolution;
2. $H(z, \lambda(t)) \rightarrow H_\lambda(z)$ with $z \equiv (q, p)$;
3. $z_0 \equiv z(0) \rightarrow z \equiv z_\lambda(t)$ *deterministic* trajectory; $dW = \lambda'(t) \partial_\lambda H_\lambda(z) dt$
 $z_0 \in \rho_0(z_0) \equiv \mathbf{Z}_0^{-1} \exp[-\beta H_0] \rightarrow \rho(z, t) = \rho_0(z_0)$ [$\neq \rho_1(z)$ for $t=t_f$]
(*Liouville theorem*);
4.
$$\begin{aligned} \langle \exp(-\beta W) \rangle &= \int dz \rho(z, t_f) \exp[-\beta \int_0^{t_f} \lambda'(t) \partial_\lambda H_\lambda(z) dt] = \\ &= \int dz \rho_0(z_0) \exp[-\beta (H_1 - H_0)] = \\ &= \mathbf{Z}_1 \mathbf{Z}_0^{-1} = \\ &= \exp(-\beta \Delta F) \end{aligned}$$
5. Now add heat bath: $H(z, z_r) = H(z) + H_{\text{res}}(z_r) + h_{\text{int}}(z, z_r)$ and assume $h_{\text{int}}(z, z_r)$ small

After subtracting the contribution arising from the entropy loss due to the stretching of the molecular handles, $\Delta G^{\text{handle}} = 23.8 \text{ kcal/mol}$, and of the extended single-stranded RNA, $\Delta G^{\text{ssRNA}} = 23.7 \pm 1 \text{ kcal/mol}$, we obtain $\Delta G_0 = 37.2 \pm 1 \text{ kcal/mol}$ (at 25°C, in 100 mM Tris-HCl, pH 8.1, 1 mM EDTA), in excellent agreement with the result obtained using the Visual OMP by DNA Software, Inc. $\Delta G_0 = 38 \text{ kcal/mol}$ (at 25° C, in 100 mM NaCl).

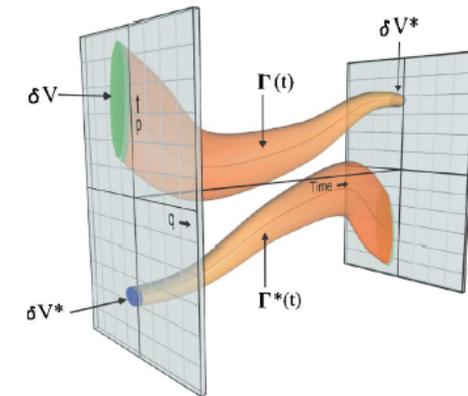
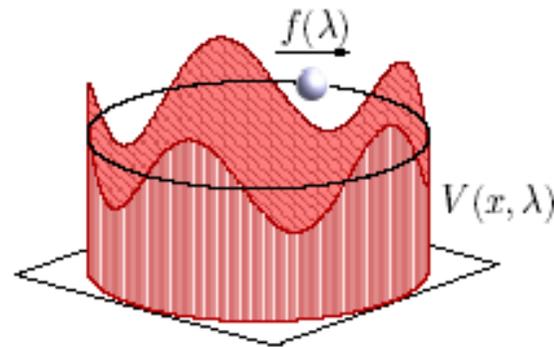
Genetic Computer Group (or Wisconsin) package

$1 k_B T \sim 0.6 \text{ kcal/mol}$ at 25°C

Experimental tests: Gallavotti Cohen FT

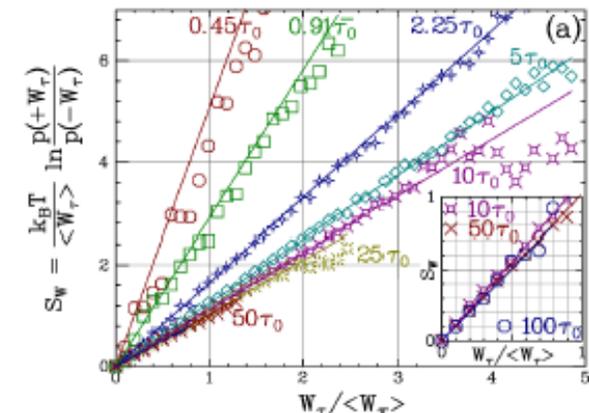
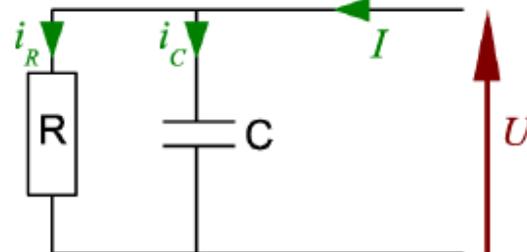
- In colloids: e.g., dragging micro-particles through water (Evans, 2004)

plastic bead
in an optical trap
at constant v



- In electrical circuits: more controllable dissipative system (Ciliberto, 2005)

pumped circuit:
fewer biases,
more trajectories



Fluctuation th. #1: Gallavotti-Cohen ('95)

FD for steady-state systems (SSS):

- time-reversal invariant SSS
- an external agent continuously produces heat by acting on the system; heat gets transferred to the bath. Sure, $\langle S \rangle = \langle Q \rangle / T > 0$, average total entropy increase of system+bath in a time interval t
- system entropy production (rate): $\sigma = Q/Tt$ from system \rightarrow bath, trajectory dependent (fluctuates!) with t -dependent p.d. $P_t(\sigma)$

$$\lim_{t \rightarrow \infty} \frac{k_B}{t} \ln \left(\frac{P_t(\sigma)}{P_t(-\sigma)} \right) = \sigma.$$

SSS are more likely to deliver a certain amount of heat to the bath, $\sigma > 0$, than to absorb it from the bath, $\sigma < 0$.

II law of thermodynamics recovered for macro-systems: for $\sigma \rightarrow \infty$

$$P_t(\sigma) / P_t(-\sigma) \rightarrow \infty$$

heat absorption becomes insignificant!

- $t \rightarrow \infty$ 'means' $t \gg$ all relaxation time scales in the system;
- molecular motors can move by rectifying thermal fluctuations (ratchets), while producing heat in average;
- Loschmidt vs Boltzmann (1876)

Q: if the microscopic law of mechanics are invariant under time-reversal, how can you rule out entropy decreasing evolutions that violate the II law?

A: time-reversed trajectories do occur, but they get vanishingly rare with system size.

Fluctuation th. #2: Jarzynski equality ('97)

- n.e. process with protocol $\mathbf{X}(t): \mathbf{X}_A \rightarrow \mathbf{X}_B$
 \mathbf{X} control parameter; $X(0) = X_A$ initial equilibrium state;
- [system in contact with heat bath at temperature T];
- $X(t_f) = X_B$ n.e. final state; equilibration follows for $t \rightarrow \infty$ with $X(t > t_f) = X_B$

J.E.

$$\exp\left(-\frac{\Delta G}{k_B T}\right) = \left\langle \exp\left(-\frac{W}{k_B T}\right) \right\rangle,$$

ΔG free-energy difference between equilibrium states \mathbf{X}_A , \mathbf{X}_B ;

$\langle \dots \rangle$ average over repeated realizations of the same protocol $\mathbf{X}(t): \mathbf{X}_A \rightarrow \mathbf{X}_B$